

Separation of B^{-1} -Convex Sets by B^{-1} -Measurable Maps

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A subset A of $\mathbb{R}_{++}^n$ is B^{-1} -convex if for all $x_1, x_2 \in A$ and all $t \geq 1$ one has $tx_1 \wedge x_2 \in A$. These sets were first investigated in [2, 3, 7]. In this paper, we establish separation and Hahn-Banach like Theorem for B^{-1} -convex sets.

Keywords: B -convexity, B^{-1} -convexity, half spaces, gauges, co-gauges, separation, B^{-1} -measurable maps

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1. Introduction

B -convexity concept is determined in [4], properties B -convex sets and functions are given in [1, 4, 5, 6], separation properties are investigated in [5, 6].

B^{-1} -convexity concept is given in [2, 7], some important properties of B^{-1} -convex sets are investigated in [2, 3], the application to economy is given in [7]. In this paper, functional Hahn-Banach like separation properties in B^{-1} -convexity are established.

The outline of the paper as follows:

In second section, required attainments to article are introduced; B^{-1} -convex sets, B^{-1} -convex hull, gauge and co-gauge functions are defined and some algebraic separation properties are given.

In third section, properties of B^{-1} -measurable maps and the relations of them with half-spaces are investigated and analytic separation theorems are proved for disjoint B^{-1} -convex sets.

In this paper, the following notations are used:

$$I = \{1, 2, \dots, n\};$$

$$\mathbb{R}_+^n = \{x = (x_1, x_2, \dots, x_n) : x_i \geq 0, i = \overline{1, n}\};$$

$$\mathbb{R}_{++}^n = \{x = (x_1, x_2, \dots, x_n) : x_i > 0, i = \overline{1, n}\};$$

$$\text{for } x \in \mathbb{R}_+^n, I(x) = \{i \in I : x_i \neq 0\};$$

$$[A] \text{ is the } B^{-1}\text{-convex hull of } A.$$

$$K = \mathbb{R} \setminus \{0\}$$

$$\overline{\mathbb{R}} =] - \infty, +\infty]$$

2. Preliminaries

Let us give some definitions and theorems with respect to B^{-1} -convexity (given in [2]).

Definition 2.1. A set A in $\mathbb{R}_{++}^n$ is B^{-1} -convex if for all $x_1, \dots, x_m \in A$ and all $t_1, \dots, t_m \in [1, \infty)$ such that $\min\{t_1, \dots, t_m\} = 1$ one has $\bigwedge_{i=1}^m t_i x_i \in A$, where $\bigwedge$ denotes the minimum with respect to partial order relation on $\mathbb{R}_+^n$ associated to the positive cone, that is, the coordinatewise minimum.

The definition of B^{-1} -convexity in K^n as $K = \mathbb{R} \setminus \{0\}$ was given in [2].

Below theorem allows to define B^{-1} -convex sets more simply [2].

Theorem 2.2. A subset A of $\mathbb{R}_{++}^n$ is B^{-1} -convex if and only if for all $x_1, x_2 \in A$ and all $t \in [1, \infty)$ one has $tx_1 \wedge x_2 \in A$.

In [4], the following proposition is proved for B -convexity.

Proposition 2.3. If A is a B -convex subset of $\mathbb{R}_+^n$ then

$$U_\infty(A, \delta) = \{x \in \mathbb{R}_+^n : \exists y \in A, \|x - y\|_\infty < \delta\}$$

is also B -convex set.

This proposition is not valid in B^{-1} -convexity, that is, for a B^{-1} -convex subset A of $\mathbb{R}_{++}^n$, $U_\infty(A, \delta)$ may not be always B^{-1} -convex. A counterexample is given in [3].

Now, for a set $A \subset \mathbb{R}_{++}^n$, we define a different neighborhood concept.

Definition 2.4. Let A be a subset of $\mathbb{R}_{++}^n$. A set

$$U_\infty^r(A, \delta) = \{x \in \mathbb{R}_{++}^n : \exists y \in A, \exists \lambda > 0, x = \lambda y, |1 - \lambda| \|y\|_\infty < \delta\}$$

is called radial δ -neighborhood of A .

Proposition 2.5. *If A is a B^{-1} -convex subset of $\mathbb{R}_{++}^n$, then $U_{\infty}^r(A, \delta)$ is also B^{-1} -convex set.*

Proof. Let $x', x'' \in U_{\infty}^r(A, \delta)$. We will show that for all $t \geq 1$, $x = tx' \wedge x'' \in U_{\infty}^r(A, \delta)$.

$$x' \in U_{\infty}^r(A, \delta) \Rightarrow \exists y' \in A, \exists \lambda' > 0, x' = \lambda' y', \quad |1 - \lambda'| \|y'\|_{\infty} < \delta \quad (1)$$

$$x'' \in U_{\infty}^r(A, \delta) \Rightarrow \exists y'' \in A, \exists \lambda'' > 0, x'' = \lambda'' y'', \quad |1 - \lambda''| \|y''\|_{\infty} < \delta. \quad (2)$$

Then, $x = tx' \wedge x'' = t\lambda' y' \wedge \lambda'' y''$.

There are two cases:

Case I. Let $t\lambda' \geq \lambda''$. Hence, we have $x = \lambda'' \left(\frac{t\lambda'}{\lambda''} y' \wedge y'' \right) = \lambda y$. Here, $\lambda = \lambda'' > 0$ and $y = \frac{t\lambda'}{\lambda''} y' \wedge y'' \in A$ (since $\frac{t\lambda'}{\lambda''} \geq 1$ and A is B^{-1} -convex.). We have to show that $|1 - \lambda| \|y\|_{\infty} < \delta$. Coordinates of y can equal to one of the following two value:

$$y_i = \begin{cases} \frac{t\lambda'}{\lambda''} y'_i, & \text{if } \frac{t\lambda'}{\lambda''} y'_i < y''_i, \\ y''_i, & \text{if } \frac{t\lambda'}{\lambda''} y'_i \geq y''_i. \end{cases} \quad (3)$$

If $\|y\|_{\infty} = \frac{t\lambda'}{\lambda''} y'_i$, from (3) and (2), we obtain

$$|1 - \lambda| \|y\|_{\infty} = |1 - \lambda''| \frac{t\lambda'}{\lambda''} y'_i < |1 - \lambda''| y''_i < \delta.$$

If $\|y\|_{\infty} = y''_i$, from (2) we have

$$|1 - \lambda| \|y\|_{\infty} = |1 - \lambda''| y''_i < \delta.$$

Case II. Let $t\lambda' < \lambda''$. Thus, $x = t\lambda' \left(y' \wedge \frac{\lambda''}{t\lambda'} y'' \right) = \lambda y$. Here, $\lambda = t\lambda' > 0$ and $y = y' \wedge \frac{\lambda''}{t\lambda'} y'' \in A$ (since $\frac{\lambda''}{t\lambda'} > 1$ and A is B^{-1} -convex.). We have to show that $|1 - \lambda| \|y\|_{\infty} < \delta$. Coordinates of y can take one of the following two value:

$$y_i = \begin{cases} y'_i, & \text{if } y'_i < \frac{\lambda''}{t\lambda'} y''_i, \\ \frac{\lambda''}{t\lambda'} y''_i, & \text{if } y'_i \geq \frac{\lambda''}{t\lambda'} y''_i. \end{cases} \quad (4)$$

When $\|y\|_{\infty} = y'_i$,

$$|1 - \lambda| \|y\|_{\infty} = |1 - t\lambda'| y'_i.$$

If $1 - t\lambda' \geq 0$, then from (1), we obtain

$$|1 - \lambda| \|y\|_{\infty} = (1 - t\lambda') y'_i < (1 - \lambda') y'_i < \delta.$$

And, if $1 - t\lambda' < 0$, then taking into account that $1 < t\lambda' < \lambda''$ and (4), (2); we have

$$\begin{aligned} |1 - \lambda| \|y\|_{\infty} &= (t\lambda' - 1) y'_i < (t\lambda' - 1) \frac{\lambda''}{t\lambda'} y''_i \\ &= \left(\lambda'' - \frac{\lambda''}{t\lambda'} \right) y''_i < (\lambda'' - 1) y''_i < \delta. \end{aligned}$$

In the other case, that is, when $\|y\|_{\infty} = \frac{\lambda''}{t\lambda'} y''_i$, it is $|1 - \lambda| \|y\|_{\infty} = |1 - t\lambda'| \frac{\lambda''}{t\lambda'} y''_i$.

Again, if $1 - t\lambda' \geq 0$, then from $t \geq 1$ and (4), (1), we obtain

$$|1 - \lambda| \|y\|_{\infty} = (1 - t\lambda') \frac{\lambda''}{t\lambda'} y''_i < (1 - \lambda') y'_i < \delta.$$

If $1 - t\lambda' < 0$, then from $1 < t\lambda' < \lambda''$ and (2), we have

$$|1 - \lambda| \|y\|_{\infty} = (t\lambda' - 1) \frac{\lambda''}{t\lambda'} y''_i = \left(\lambda'' - \frac{\lambda''}{t\lambda'} \right) y''_i < (\lambda'' - 1) y''_i < \delta.$$

Consequently, we have shown that $x = tx' \wedge x'' \in U_{\infty}^r(A, \delta)$.

Thus it has been proved that the set $U_{\infty}^r(A, \delta)$ is B^{-1} -convex set. $\square$

Closure and interior of B^{-1} -convex sets are also B^{-1} -convex [3].

Of particular interest are the B^{-1} -convex sets whose complements are also B^{-1} -convex, those sets are called half-spaces.

Definition 2.6. For a set $A \subset \mathbb{R}_{++}^n$, the intersection of all the B^{-1} -convex subset of $\mathbb{R}_{++}^n$ containing A is called the B^{-1} -convex hull of A and denoted by $\llbracket A \rrbracket$.

The following properties will be necessary in the future.

Lemma 2.7. For all subsets A of $\mathbb{R}_{++}^n$ and for all point p, we have

$$\llbracket A \cup \{p\} \rrbracket = \bigcup_{x \in \llbracket A \rrbracket} \llbracket \{x, p\} \rrbracket.$$

Proof. We assume that $A \neq \emptyset$ and $y \in \llbracket A \cup \{p\} \rrbracket$. Then, there exist $x_1, \dots, x_k \in A$ and $\eta_1, \dots, \eta_{k+1} \in [1, \infty)$ such that $\min \{\eta_1, \dots, \eta_k, \eta_{k+1}\} = 1$ and $y = \eta_1 x_1 \wedge \dots \wedge \eta_k x_k \wedge \eta_{k+1} p$. Let $\mu = \min \{\eta_1, \dots, \eta_k\}$ and $\mu_i = \frac{\eta_i}{\mu}$ for $i = \overline{1, k}$. Hence $x = \mu_1 x_1 \wedge \dots \wedge \mu_k x_k \in \llbracket A \rrbracket$ and $y = \mu x \wedge \eta_{k+1} p \in \llbracket \{x, p\} \rrbracket$ since $\min \{\mu, \eta_{k+1}\} = 1$.

We prove the other side: If $y \in \bigcup_{x \in \llbracket A \rrbracket} \llbracket \{x, p\} \rrbracket$ then, there exist $x' \in \llbracket A \rrbracket$ such that $y \in \llbracket \{x', p\} \rrbracket$. Since $x' \in \llbracket A \rrbracket$, for $\min \{\mu_1, \dots, \mu_k\} = 1$ and $x'_1, \dots, x'_k \in A$ we can write $x' = \mu_1 x'_1 \wedge \dots \wedge \mu_k x'_k$. $y \in \llbracket \{x', p\} \rrbracket$ hence, for $\eta_1, \eta_2 \in [1, \infty)$, $\min \{\eta_1, \eta_2\} = 1$,

$$\begin{aligned} y &= \eta_1 x' \wedge \eta_2 p = \eta_1 (\mu_1 x'_1 \wedge \dots \wedge \mu_k x'_k) \wedge \eta_2 p \\ &= (\eta_1 \mu_1) x'_1 \wedge \dots \wedge (\eta_1 \mu_k) x'_k \wedge \eta_2 p. \end{aligned}$$

Consequently, for

$$x'_1, \dots, x'_k, p \in A \bigcup \{p\}, \quad \eta_1 \mu_1, \eta_1 \mu_2, \dots, \eta_1 \mu_k, \eta_2 \in [1, \infty)$$

and

$$\min \{\eta_1 \mu_1, \eta_1 \mu_2, \dots, \eta_1 \mu_k, \eta_2\} = 1$$

thus

$$y = (\eta_1 \mu_1) x'_1 \wedge \dots \wedge (\eta_1 \mu_k) x'_k \wedge \eta_2 p \in \llbracket A \bigcup \{p\} \rrbracket. \quad \square$$

Proposition 2.8 (Pash-Peano). *For all quintuple (a, b_1, b_2, c_1, c_2) of points of $\mathbb{R}_{++}^n$ such that $c_i \in \llbracket \{a, b_i\} \rrbracket$ we have $\llbracket \{b_1, c_2\} \rrbracket \cap \llbracket \{b_2, c_1\} \rrbracket \neq \emptyset$.*

Proof. We have to show that the following system of equations has a solution

$$\begin{cases} \eta_1 c_1 \wedge \mu_2 b_2 = \eta_2 c_2 \wedge \mu_1 b_1 \\ \min \{\eta_1, \mu_2\} = 1 \\ \min \{\eta_2, \mu_1\} = 1 \end{cases} \quad (5)$$

Since $c_i \in \llbracket a, b_i \rrbracket$ we can write $c_i = \rho_i a \wedge \alpha_i b_i$ with $\min \{\rho_i, \alpha_i\} = 1$; a substitution in the first line of (5) yields

$$(\eta_1 \rho_1) a \wedge (\eta_1 \alpha_1) b_1 \wedge \mu_2 b_2 = (\eta_2 \rho_2) a \wedge (\eta_2 \alpha_2) b_2 \wedge \mu_1 b_1 \quad (6)$$

Given ρ_i and $\alpha_i, i = 1, 2$, one can easily solve (6) for η_i and $\mu_i, i = 1, 2$ in the following way

$$\eta_1 = 1 \quad \text{and} \quad \eta_2 = \frac{\rho_1}{\rho_2} \quad \text{if } \rho_1 > \rho_2 \quad (7)$$

$$\eta_1 = \frac{\rho_2}{\rho_1} \quad \text{and} \quad \eta_2 = 1 \quad \text{if } \rho_1 < \rho_2 \quad (8)$$

$$\eta_1 = \eta_2 = 1 \quad \text{if } \rho_1 = \rho_2 \quad (9)$$

$$\mu_i = \eta_i \alpha_i \quad (10)$$

This solution of (6) is also a solution of (5) if $\min \{\eta_1, \mu_2\} = \min \{\eta_2, \mu_1\} = 1$; let us see that this is indeed the case. There are, formally, three cases to consider, namely (7), (8) and (9). In the first case, (7) we have $\min \{\eta_1, \mu_2\} = \eta_1 = 1$ and $\min \{\rho_1, \alpha_1\} = 1$ with $\rho_1 > \rho_2 \geq 1$ from which we obtain $\alpha_1 = 1$ and $\mu_1 = \eta_1 = 1$; we have shown that $\min \{\eta_2, \mu_1\} = 1$. The second case, that is (8), is treated similarly; as for (9) there is nothing to prove since $\eta_1 = \eta_2 = 1$. $\square$

Proposition 2.9 (The Stone-Kakutani Property). *If C_1 and C_2 are disjoint B^{-1} -convex sets, then there exists a B^{-1} -convex set $D \subset \mathbb{R}_{++}^n$ such that $\mathbb{R}_{++}^n \setminus D$ is also B^{-1} -convex, $C_1 \subset D$ and $C_2 \subset \mathbb{R}_{++}^n \setminus D$.*

Proof. Let Z be the family of pairs of disjoint B^{-1} -convex sets (D_1, D_2) such that $C_i \subset D_i$ partially ordered by $(D_1, D_2) \subset (D'_1, D'_2)$ if $D_i \subset D'_i$. The pair (C_1, C_2) belong to Z and if $\mathcal{C} = \{(D_{1,\lambda}, D_{2,\lambda}) : \lambda \in \Lambda\}$ is a chain in Z , then $(\bigcup_{\lambda \in \Lambda} D_{1,\lambda}, \bigcup_{\lambda \in \Lambda} D_{2,\lambda}) \in Z$ since an up-directed union of B^{-1} -convex sets is B^{-1} -convex and, as can easily be seen, $(\bigcup_{\lambda \in \Lambda} D_{1,\lambda}) \cap (\bigcup_{\lambda \in \Lambda} D_{2,\lambda}) = \emptyset$; by Zorn's lemma there is a maximal element (H_1, H_2) in Z . Assume that there is a point a in $\mathbb{R}_{++}^n \setminus (H_1 \cup H_2)$; from the maximality of the pair (H_1, H_2) we have $\llbracket H_1 \cup \{a\} \rrbracket \cap H_2 \neq \emptyset$ and $\llbracket H_2 \cup \{a\} \rrbracket \cap H_1 \neq \emptyset$, take a point $c_1 \in \llbracket H_1 \cup \{a\} \rrbracket \cap H_2$ and a point $c_2 \in \llbracket H_2 \cup \{a\} \rrbracket \cap H_1$. By Lemma 2.7 there exist $b_i \in H_i$ such that $c_i \in \llbracket \{a, b_i\} \rrbracket$. By the Pash-Peano Property there exists a point u in $\llbracket \{b_1, c_2\} \rrbracket \cap \llbracket \{b_2, c_1\} \rrbracket$. From $b_1, c_2 \in H_1$ and $b_2, c_1 \in H_2$ we obtain $u \in H_1 \cap H_2$ which is impossible since the pair (H_1, H_2) is in Z . $\square$

We need the following definitions (see [8] for details). A set $U \subset \mathbb{R}^n$ is called radiant if $x \in U, t \in]0, 1]$ implies $tx \in U$. A set $V \subset \mathbb{R}^n$ is called co-radiant if $x \in V, t \geq 1$ implies $tx \in V$. The Minkowski gauge $\mu_U : \mathbb{R}^n \rightarrow [0, +\infty]$ of the radiant set U is defined by

$$\mu_U(x) = \inf \{ \lambda \in]0, +\infty[: x \in \lambda U \}, \quad x \in \mathbb{R}^n.$$

The Minkowski co-gauge $\nu_V : \mathbb{R}^n \rightarrow [0, +\infty]$ of the co-radiant set V is defined by

$$\nu_V(x) = \sup \{ \lambda \in]0, +\infty[: x \in \lambda V \}, \quad x \in \mathbb{R}^n.$$

As is known, $\inf \emptyset = +\infty$ and $\sup \emptyset = 0$.

If U is radiant set then $V = \mathbb{R}^n \setminus U$ is co-radiant and $\nu_V = \mu_U$. If V is co-radiant then $U = \mathbb{R}^n \setminus V$ is radiant and $\mu_U = \nu_V$.

Note that both μ_U and ν_V are positively homogeneous functions (A function $f : \mathbb{R}^n \rightarrow [0, +\infty]$ is called positively homogeneous if $f(\lambda x) = \lambda f(x)$ for all $\lambda \in]0, +\infty[$).

A set $U \subset \mathbb{R}^n$ is called radially closed if

$$(x \in \mathbb{R}^n, \lambda_k > 0, \lambda_k x \in U, k = 1, 2, \dots, \lambda_k \rightarrow \lambda) \Rightarrow \lambda x \in U.$$

A set U is called radially open if its complement $\mathbb{R}^n \setminus U$ is radially closed.

3. Separation in B^{-1} -convexity

3.1. B^{-1} -measurable maps and half-spaces

Definition 3.1. Let $K = \mathbb{R} \setminus \{0\}$ and $\overline{\mathbb{R}} =]-\infty, +\infty]$. A map $f : K^n \rightarrow \overline{\mathbb{R}}^m$ is B^{-1} -measurable if for all B^{-1} -convex set C of $\overline{\mathbb{R}}^m$ the inverse image $f^{-1}(C)$ is a B^{-1} -convex set in K^n .

Theorem 3.2. For a map $f : K^n \rightarrow \overline{\mathbb{R}}$, f is B^{-1} -measurable if and only if for all $t \in \mathbb{R}$ the sets $\{x : f(x) \leq t\}$ and $\{x : f(x) \geq t\}$ are B^{-1} -convex.

Proof. Let f be B^{-1} -measurable. Then, for all subset $C \subset \mathbb{R}$ which is B^{-1} -convex, $f^{-1}(C)$ is B^{-1} -convex set. The sets $C_1 = (-\infty, t]$ and $C_2 = [t, +\infty)$ are B^{-1} -convex for all $t \in \mathbb{R}$. Hence, the sets

$$f^{-1}(C_1) = \{x \mid f(x) \leq t\} \quad \text{and} \quad f^{-1}(C_2) = \{x \mid f(x) \geq t\}$$

are B^{-1} -convex.

Now, for all $t \in \mathbb{R}$, let $\{x \mid f(x) \leq t\}$ and $\{x \mid f(x) \geq t\}$ be B^{-1} -convex sets. In $\mathbb{R}$, each B^{-1} -convex sets are intervals (finite or infinite). For instance, let $C=[a,b]$, in this case

$$\begin{aligned} f^{-1}(C) &= f^{-1} \left(\bigcup_{n=1}^{\infty} \left(-\infty, b - \frac{1}{n} \right] \cap [a, +\infty) \right) \\ &= \left(\bigcup_{n=1}^{\infty} f^{-1} \left(-\infty, b - \frac{1}{n} \right] \right) \cap f^{-1}([a, +\infty)) \\ &= \left(\bigcup_{n=1}^{\infty} \left\{ x \mid f(x) \leq b - \frac{1}{n} \right\} \right) \cap \{x \mid f(x) \geq a\} .. \quad \square \end{aligned}$$

Theorem 3.3. A map $f : \mathbb{R}_{++}^n \rightarrow [0, \infty]$ is B^{-1} -measurable if and only if

$$\min \{f(x_1), f(x_2)\} \leq f(\lambda x_1 \wedge x_2) \leq \max \{f(x_1), f(x_2)\}$$

for all $x_1, x_2 \in \mathbb{R}_{++}^n$ and for all $\lambda \in [1, \infty)$.

Proof. If f is B^{-1} -measurable, it follows from Theorem 3.2 that the sets $\{x : f(x) \leq t\}$ and $\{x : f(x) \geq t\}$ are B^{-1} -convex for all t . Hence, for $x_1, x_2 \in \mathbb{R}_{++}^n$, $\{x : f(x) \leq \max \{f(x_1), f(x_2)\}\}$ and $\{x : f(x) \geq \min \{f(x_1), f(x_2)\}\}$ are B^{-1} -convex. Since $x_1, x_2 \in \{x : f(x) \leq \max \{f(x_1), f(x_2)\}\}$ and the set is B^{-1} -convex, $f(\lambda x_1 \wedge x_2) \leq \max \{f(x_1), f(x_2)\}$ for all $\lambda \in [1, +\infty)$. In a similar way we can show the left side of the inequality.

Now, let us assume that the inequality is valid and we show that the sets of $\{x : f(x) \leq t\}$ and $\{x : f(x) \geq t\}$ are B^{-1} -convex for all t . If $x_1, x_2 \in \{x : f(x) \leq t\}$, then $f(x_1) \leq t, f(x_2) \leq t$. From the inequalities, for $\lambda \in [1, +\infty)$ we have $f(\lambda x_1 \wedge x_2) \leq \max \{f(x_1), f(x_2)\} \leq t$, consequently, $\lambda x_1 \wedge x_2 \in \{x : f(x) \leq t\}$. B^{-1} -convexity of the second set is shown by the same way. $\square$

Half-spaces of B -convexity are either radiant or co-radiant. For B^{-1} -convexity, it can be shown that same property is obtained, that is, a half-space in B^{-1} -convexity is radiant or co-radiant.

Lemma 3.4.

- 1) Let $U \in \mathbb{R}_{++}^n$ be a radiant set.
 (a) If U is B^{-1} -convex, then

$$\mu_U(tx \wedge y) \leq \max \{\mu_U(x), \mu_U(y)\} \quad \text{for all } x, y \in \mathbb{R}_{++}^n, t \in [1, \infty) \quad (11)$$

- (b) If U is radially closed or radially open and (11) holds, then U is B^{-1} -convex.
- 2) Let $V \subset \mathbb{R}_{++}^n$ be a co-radiant set.
- (a) If V is B^{-1} -convex, then

$$\nu_V(tx \wedge y) \geq \min \{\nu_V(x), \nu_V(y)\} \quad \text{for all } x, y \in \mathbb{R}_{++}^n, t \in [1, \infty) \quad (12)$$

- (b) If V is radially closed or radially open and (12) holds, then V is B^{-1} -convex.

Proof. 1) Let U be a radiant B^{-1} -convex set. Consider points $x, y \in \mathbb{R}_{++}^n$ and $t \in [1, \infty)$. Assume for the sake of definiteness that $\mu_U(x) \leq \mu_U(y) < \infty$. If $r > \mu_U(y)$ then $x \in rU, y \in rU$. From $r^{-1}(tx \wedge y) = r^{-1}tx \wedge r^{-1}y$ we have $r^{-1}(tx \wedge y) \in U$; this shows that (11) holds. If either $\mu_U(tx) = \infty$ or $\mu_U(y) = \infty$ then (11) is obvious.

Let U be radiant. If U is radially closed, then $U = \{x \in \mathbb{R}_{++}^n : \mu_U(x) \leq 1\}$, if U is radially open then $U = \{x \in \mathbb{R}_{++}^n : \mu_U(x) < 1\}$. In both cases (11) implies that U is a B^{-1} -convex set.

2) Let V be a co-radiant and B^{-1} -convex set. Consider points $x, y \in \mathbb{R}_{++}^n$ and a number $t \in [1, \infty)$. Assume for the sake of definiteness that $0 < \nu_V(y) \leq \nu_V(x) \leq \infty$. Let $0 < r < \nu_V(y)$ then $x \in rV, y \in rV$. Since V is B^{-1} -convex set, $r^{-1}(tx \wedge y) = tr^{-1}x \wedge r^{-1}y \in V$, in other words, $tx \wedge y \in rV$. Hence (12) holds. If either $\nu_V(x) = 0$ or $\nu_V(y) = 0$ then (12) is obvious.

If V is either radially closed or open and (12) holds, then clearly V is a B^{-1} -convex set. $\square$

Proposition 3.5. (1) Let H be a radiant half-space. Then for all $x, y \in \mathbb{R}_{++}^n$ and $t \in [1, +\infty)$

$$\min \{\mu_H(x), \mu_H(y)\} \leq \mu_H(tx \wedge y) \leq \max \{\mu_H(x), \mu_H(y)\} \quad (13)$$

If H is B^{-1} -convex, radiant, either radially closed or open and the left-hand inequality in (13) holds, then H is a half-space.

(2) Let H be a co-radiant half-space. Then for all $x, y \in \mathbb{R}_{++}^n$ and $t \in [1, +\infty)$

$$\min \{\nu_H(x), \nu_H(y)\} \leq \nu_H(tx \wedge y) \leq \max \{\nu_H(x), \nu_H(y)\} \quad (14)$$

If H is B^{-1} -convex, co-radiant, either radially closed or open and the right-hand inequality in (14) holds, then H is a half-space.

Proof. (1) Let H be a radiant half-space and $x, y \in \mathbb{R}_{++}^n, t \in [1, \infty)$. Since H is B^{-1} -convex and radiant it follows from (11) that the right-hand inequality in (13) holds. Since $C = \mathbb{R}_{++}^n \setminus H$ is B^{-1} -convex and co-radiant it follows from (12) that

$$\nu_C(tx \wedge y) \geq \min \{\nu_C(x), \nu_C(y)\}$$

From $\mu_H = \nu_C$, we obtain the left-hand inequality in (13).

Let H be B^{-1} -convex and radially closed, then C is radially open. The left-hand inequality in (13) can be presented as $\min\{\nu_C(x), \nu_C(y)\} \leq \nu_C(tx \wedge y)$. Applying Lemma 3.4, we conclude that C is B^{-1} -convex, hence H is half-space. A similar argument can be used if H is radially open.

(2) Let H be a co-radiant half-space and $x, y \in \mathbb{R}_{++}^n, t \in [1, \infty)$. Since H is B^{-1} -convex and co-radiant it follows from (12) that left-hand inequality in (14) holds. Since C is B^{-1} -convex and radiant it follows from (11) that

$$\mu_C(tx \wedge y) \leq \max\{\mu_C(x), \mu_C(y)\}$$

This implies the right-hand inequality in (14).

Let H be B^{-1} -convex and radially closed, then C is radially open. The right-hand inequality in (14) can be presented as $\mu_C(tx \wedge y) \leq \max\{\mu_C(x), \mu_C(y)\}$. Applying Lemma 3.4 we conclude that C is B^{-1} -convex, hence H is a half-space. The similar argument can be used if H is radially open. $\square$

As one can easily see that the gauge of a radiant half-space and the co-gauge of a co-radiant half-space are positively homogeneous B^{-1} -measurable maps.

3.2. Separation of B^{-1} -convex sets by a map

Definition 3.6. Let A and B be two sets.

- (i) A and B are weakly separated by a map f if $\sup_{x \in A} f(x) \leq \inf_{x \in B} f(x)$ or $\sup_{x \in B} f(x) \leq \inf_{x \in A} f(x)$.
- (ii) A and B are separated by a map f if there exists a real number r such that either $\forall (x, y) \in A \times B$ $f(x) < r < f(y)$ or $\forall (x, y) \in A \times B$ $f(y) < r < f(x)$.
- (iii) A and B are strictly separated by a map f if $\sup_{x \in A} f(x) < \inf_{x \in B} f(x)$ or $\sup_{x \in B} f(x) < \inf_{x \in A} f(x)$.

Theorem 3.7. Let C_1 and C_2 be disjoint and B^{-1} -convex sets.

- (1) C_1 and C_2 can be weakly separated by a B^{-1} -measurable positively homogeneous map.
- (2) If, $\inf_{(x,y) \in C_1 \times C_2} \|x - y\|_\infty > 0$ and there exists a vector $u \in \mathbb{R}_{++}^n$ such that $C_1 \cup C_2 \subset \mathbb{R}_{++}^n + u$, then C_1 and C_2 can be separated by a B^{-1} -measurable positively homogeneous map.
- (3) If, with the condition in (2), either C_1 or C_2 is bounded then they can be strictly separated by a B^{-1} -measurable positively homogeneous map.

Proof. (1) Let C_1 and C_2 be disjoint and B^{-1} -convex subsets of $\mathbb{R}_{++}^n$; by Proposition 2.9 (Stone-Kakutani Property) there exists a half-space B such that $C_1 \subset B$ and $C_2 \subset \mathbb{R}_{++}^n \setminus B$ and we can assume that B is radiant. Hence, for all $x \in C_1, \mu_B(x) \leq 1$ and for all $x \in C_2, \mu_B(x) \geq 1$.

(2) Let $\eta = \inf_{(x,y) \in C_1 \times C_2} \|x - y\|_\infty$ and, for all subset $A \subset \mathbb{R}_{++}^n$ let $U_\infty^r(A; \delta) = \{x \in \mathbb{R}_{++}^n : \exists y \in A, \exists \lambda > 0, x = \lambda y, |1 - \lambda| \|y\|_\infty < \delta\}$; if A is B^{-1} -convex then, for all $\delta \geq 0, U_\infty^r(A; \delta)$ is also B^{-1} -convex by Proposition 2.5. Since $\eta > 0$ we can

choose $u \in \mathbb{R}_{++}^n, \epsilon > 0$ such $\epsilon < \min \{\eta, \|u\|_\infty\}$ and $U_\infty^r(C_1; \epsilon) \cap U_\infty^r(C_2; \epsilon) = \emptyset$. From part (1) we find a radiant half-space H such that $U_\infty^r(C_1; \epsilon) \subset H, U_\infty^r(C_2; \epsilon) \subset \mathbb{R}_{++}^n \setminus H$ and $\sup_{x \in U_\infty^r(C_1; \epsilon)} \mu_H(x) \leq 1 \leq \inf_{x \in U_\infty^r(C_2; \epsilon)} \mu_H(x)$. If $x \in C_1$ and $t = (1 + \epsilon / (2 \|x\|_\infty))$ then $tx \in U_\infty^r(C_1; \epsilon) \subset H$, and therefore,

$$\mu_H(x) \leq \left(1 + \frac{\epsilon}{2 \|x\|_\infty}\right)^{-1} < 1$$

If $y \in C_2$ then $y \in \mathbb{R}_{++}^n + u$ and $\|y\|_\infty > \epsilon$ and therefore $s = (1 - \epsilon / (2 \|y\|_\infty))$ is strictly positive. Since $\|sy - y\|_\infty = \epsilon/2$ we have $sy \in U_\infty^r(C_2; \epsilon) \subset \mathbb{R}_{++}^n \setminus H$, and therefore $sy \notin H$ which implies that

$$1 < \left(1 - \frac{\epsilon}{2 \|y\|_\infty}\right)^{-1} \leq \mu_H(y)$$

(3) Now, assume that C_1 is bounded. There is a $v \in \mathbb{R}_{++}^n$ such that, for all $x \in C_1, \|x\|_\infty \leq \|v\|_\infty$ and therefore

$$\sup_{x \in C_1} \mu_H(x) \leq \left(1 + \frac{\epsilon}{\|v\|_\infty}\right)^{-1} < 1 \leq \inf_{y \in C_2} \mu_H(y).$$

If C_2 is bounded there is a $v \in \mathbb{R}_{++}^n$ such that, for all $y \in C_2, \|y\|_\infty \leq \|v\|_\infty$, and $\epsilon < \|v\|_\infty$; we then have

$$\sup_{x \in C_1} \mu_H(x) \leq 1 < \left(1 - \frac{\epsilon}{\|v\|_\infty}\right)^{-1} \leq \inf_{y \in C_2} \mu_H(y). \quad \square$$

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