

Dislocation Hyperbolic Kernel Function

Lennin Mallma Ramirez*, Nelson Maculan, Adilson Elias Xavier

*Systems Engineering and Computer Science Program,
Federal University of Rio de Janeiro, Brazil
lenninmr@gmail.com, maculan@cos.ufrj.br, adilson.xavier@gmail.com*

Vinicius Layter Xavier

*Institute of Mathematics and Statistics, Rio de Janeiro State University, Brazil
viniciuslx@ime.uerj.br*

Received: September 16, 2022

Accepted: October 20, 2023

A new kernel function is introduced in Mathematical Optimization. This function is called the dislocation hyperbolic kernel function. It is based on the dislocation hyperbolic function. Finally we present some applications of this new function.

Keywords: Dislocation hyperbolic function, Fenchel conjugate, kernel function, self-concordant.

2020 Mathematics Subject Classification: 46N10.

1. Introduction

In nonlinear programming a problem that is very studied is the following

$$(P) \quad \min \{f(x) \mid x \in S\}, \quad (1)$$

with $S = \{x \in \mathbb{R}^n \mid g_i(x) \geq 0, \ i = 1, \dots, m\}$,

where $f : \mathbb{R}^n \rightarrow \mathbb{R}$ and $g_i : \mathbb{R}^n \rightarrow \mathbb{R}$, $i = 1, \dots, m$. The problem (1) can be solved by a wide variety of algorithms, some of them are: the penalty and augmented Lagrangian algorithms.

In 1967, Zangwill ([31]) studied the exact penalty function (EPF) in his penalty algorithm. This function is as follows:

$$\beta \in \mathbb{R} \quad \mapsto \quad (\beta)_+ = -\min \{\beta, 0\}, \quad (2)$$

see Figure 1.1. Later EPF is smoothed and used in [27], [11], [22] and [13].

1.1. Hyperbolic penalty function

In the hyperbolic penalty algorithm (HPA), the solution to problem (P) is obtained by means of solving a sequence of subproblems, $k = 1, 2, \dots$, defined by minimization of the modified objective function

$$F(x, \lambda^k, \tau^k) = f(x) + \sum_{i=1}^m P(g_i(x), \lambda_i^k, \tau_i^k), \quad (3)$$

* Corresponding author.

where $P(\cdot, \cdot, \cdot)$ is the hyperbolic penalty function (HPF), defined as follows

$$P(y, \lambda, \tau) = -\lambda y + \sqrt{(\lambda y)^2 + \tau^2}, \quad (4)$$

where $P: (-\infty, +\infty) \times \mathbb{R}_+ \times \mathbb{R}_{++} \rightarrow \mathbb{R}$, see Figure 1.2. In HPA, the parameters λ and τ are updated. The HPF was originally proposed in [27] and studied in [28] and [29]. The HPF is equivalent to a smoothing of the penalty studied by Zangwill [31].

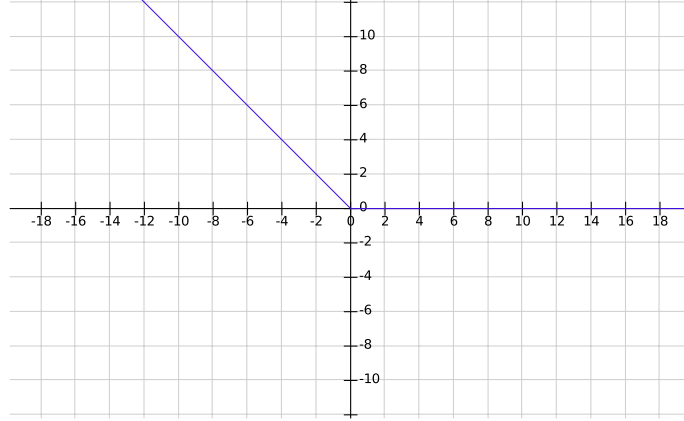


Figure 1.1: Function $(\beta)_+ = -\min\{\beta, 0\}$

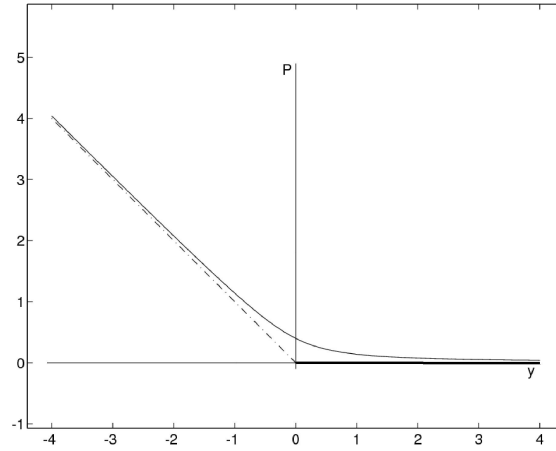


Figure 1.2: Function P

1.2. Hyperbolic augmented Lagrangian function

In the hyperbolic augmented Lagrangian algorithm (HALA), the solution to problem (P) is obtained by means of solving a subproblem, defined by the minimization of the hyperbolic augmented Lagrangian function (HALF) $L_H: \mathbb{R}^n \times \mathbb{R}_{++}^m \times \mathbb{R}_{++} \rightarrow \mathbb{R}$,

$$\begin{aligned} L_H(x, \lambda, \tau) &= f(x) + \sum_{i=1}^m P(g_i(x), \lambda_i, \tau) \\ &= f(x) + \sum_{i=1}^m \left(-\lambda_i g_i(x) + \sqrt{(\lambda_i g_i(x))^2 + \tau^2} \right), \end{aligned} \quad (5)$$

where τ is the penalty parameter that is fixed and λ is the Lagrange multiplier which is updated by means of a formula. The HALA was proposed in [28], and recently its convergence was guaranteed in [18]. Note that this function L_H belongs to class C^∞ if the involved functions $f(x)$ and $g_i(x)$, $i = 1, \dots, m$, are too.

1.3. Dislocation hyperbolic augmented Lagrangian function

We define the function $l_H : \mathbb{R}^n \times \mathbb{R}_{++}^m \times \mathbb{R}_{++} \rightarrow \mathbb{R}$, as,

$$\begin{aligned} l_H(x, \lambda, \tau) &= f(x) + \sum_{i=1}^m p(g_i(x), \lambda_i, \tau) \\ &= f(x) + \sum_{i=1}^m \left(-\lambda_i g_i(x) + \sqrt{(\lambda_i g_i(x))^2 + \tau^2} - \tau \right), \end{aligned} \quad (6)$$

where τ is the penalty parameter that is fixed and λ is the Lagrange multiplier. In [28], the dislocation hyperbolic function is mentioned as follows:

$$p(y, \lambda, \tau) = -\lambda y + \sqrt{(\lambda y)^2 + \tau^2} - \tau. \quad (7)$$

1.4. Hyperbolic smoothing function

In [30] the hyperbolic smoothing function (HSF) was introduced, in [3] this function is studied. This function is defined as

$$\Phi(x, \tau) = \frac{x + \sqrt{x^2 + \tau^2}}{2}. \quad (8)$$

The paper is organized as follows: In Section 2, we present some basic definitions. In Section 3, we introduce the dislocation hyperbolic kernel function and some of its properties are studied. In Section 4, we show some applications of the dislocation hyperbolic function. In Section 5, we show some applications of the dislocation hyperbolic kernel function. We also propose a new self-concordant function. In Section 6, we discuss some ideas for future work and conclusions from our work.

2. Preliminaries

Definition 2.1. (See [19] and [20]) A function $f \in C^3 : (0, \infty) \rightarrow (0, \infty)$ is *self-concordant* (SC) if f is convex, three times continuously differentiable, and satisfies for some constant $\alpha > 0$ the condition

$$|f'''(t)| \leq \alpha (f''(t))^{\frac{3}{2}}, \quad \forall t \in (0, \infty).$$

Definition 2.2. (See [19] and [20]) A univariate function $f \in C^3$ is said to be a *self-concordant barrier* for the domain $\mathbb{R}_+$ if it satisfies the following two conditions:

- (i) The function $f(t)$ is self-concordant.
- (ii) There exists a constant α such that $|f'(t)| \leq \alpha (f''(t))^{\frac{1}{2}}$.

The kernel function (KF) is any univariate strictly convex function $k(t)$ that is minimal at $t = 1$ and such that $k(1) = 0$. The KF is widely studied in primal-dual path-following method ([5] and [1]), also in stochastic programming [9].

Here are some examples:

Examples 2.3. (1) $k(t) = t \log(t) - t + 1$, $t \geq 0$, see, Kullback-Leible [16].

(2) $k(t) = (1 - \sqrt{t})^2$, $t \geq 0$, see, Hellinger Distance [10].

3. The dislocation hyperbolic kernel function

In this section we introduce the Dislocation Hyperbolic Kernel Function (DHKF).

3.1. Dislocation hyperbolic function

A new approach of the hyperbolic functions is studied in this section. We are going to write the expression (6) as follows

$$l_H(x, \lambda, \tau) = f(x) + \sum_{i=1}^m p(g_i(x), \lambda_i, \tau) \quad (9)$$

$$\begin{aligned} &= f(x) - \sum_{i=1}^m \left(\lambda_i g_i(x) - \sqrt{(\lambda_i g_i(x))^2 + \tau^2} + \tau \right) \\ &= f(x) - \sum_{i=1}^m \tau \left(\frac{\lambda_i g_i(x)}{\tau} - \sqrt{\left(\frac{\lambda_i g_i(x)}{\tau} \right)^2 + 1} + 1 \right). \end{aligned} \quad (10)$$

We rewrite (10) now as

$$l_H(x, \lambda, \tau) = f(x) - \sum_{i=1}^m \tau h\left(\frac{\lambda_i g_i(x)}{\tau}\right), \quad (11)$$

where the function h will be called by the dislocation hyperbolic function (DHF), and is defined as

$$h(t) = t - \sqrt{t^2 + 1} + 1,$$

with $h \in C^\infty$ and is defined $h : (-\infty, \infty) \rightarrow \mathbb{R}$, see Figure 3.1.

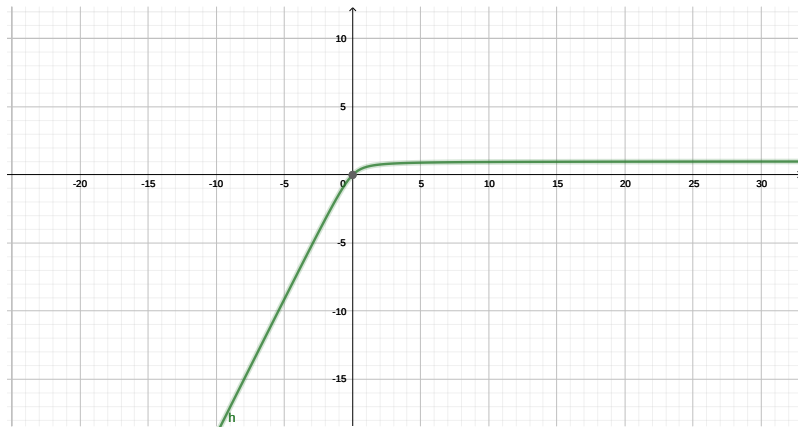


Figure 3.1: Function $h(t)$

The function h satisfies the following properties:

- (H1) (i) $h(0) = 0$.
 (ii) $\lim_{t \rightarrow +\infty} h(t) = 1$.
 (iii) $\lim_{t \rightarrow -\infty} h(t) = -\infty$.
 (H2) (i) h is increasing, i.e., $h'(t) = 1 - \frac{t}{\sqrt{t^2 + 1}} > 0, \forall t \in (-\infty, \infty)$.
 (ii) $h'(0) = 1$.
 (iii) $\lim_{t \rightarrow +\infty} h'(t) = \lim_{t \rightarrow +\infty} \left(1 - \frac{t}{|t|\sqrt{1 + \frac{1}{t^2}}}\right) = 0, t > 0$.
 (iv) $\lim_{t \rightarrow -\infty} h'(t) = \lim_{t \rightarrow -\infty} \left(1 - \frac{t}{|t|\sqrt{1 + \frac{1}{t^2}}}\right) = 2, t < 0$.
 (v) $0 < h'(t) < 2$.

See Figure 3.2.

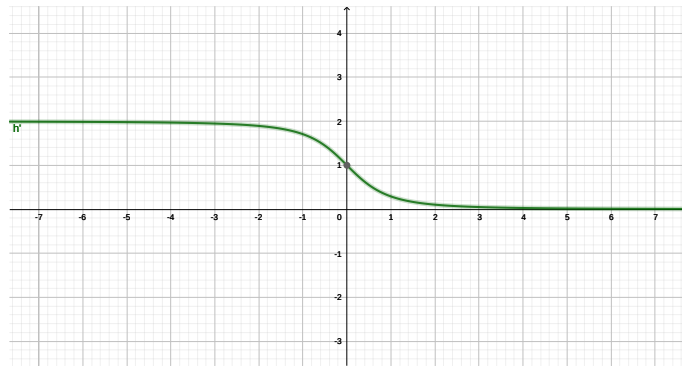


Figure 3.2: Function $h'(t)$

- (H3) (i) The h function is strictly concave, i.e.,

$$h''(t) = \frac{-1}{(t^2 + 1)^{\frac{3}{2}}} < 0, \forall t \in (-\infty, \infty).$$

- (ii) $\lim_{t \rightarrow +\infty} h''(t) = 0$.
 (iii) $\lim_{t \rightarrow -\infty} h''(t) = 0$.

See Figure 3.3.

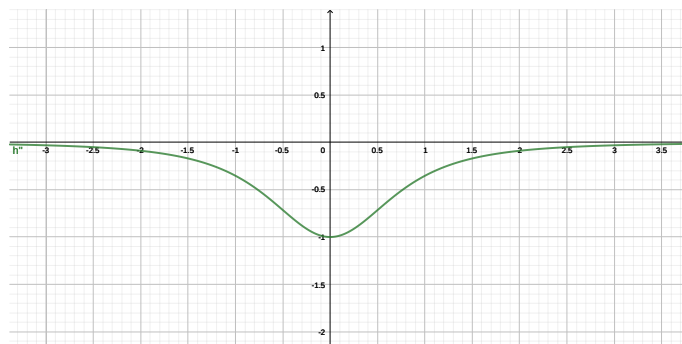


Figure 3.3: Function $h''(t)$

$$(H4) \quad \lim_{t \rightarrow 0^+} th \left(\frac{z}{t} \right) = \lim_{t \rightarrow 0^+} t \left(\frac{z}{t} - \sqrt{\left(\frac{z}{t} \right)^2 + 1 + 1} \right) = \lim_{t \rightarrow 0^+} \left(z - \sqrt{z^2 + t^2} + t \right) = 0, \\ \text{for all } z \geq 0.$$

We denote by Ψ_H this class of functions.

3.2. The Fenchel conjugate for DHF

The Fenchel conjugate of h is given by

$$h^*(s) = \inf \{ st - h(t) \mid t \in \mathbb{R} \} = st(s) - h(t(s)),$$

due to (H3) for any $0 < s < 2$ and the equation $(st - h(t))'_t = s - h'(t) = 0$. It follows that $h'(t) = s$. This can be solved for t as follows

$$1 - \frac{t}{\sqrt{t^2 + 1}} = s.$$

In this last equality we will perform some operations, in this way we will obtain the following equalities

$$(1 - s)^2 = \frac{t^2}{t^2 + 1}, \quad \text{hence } (t^2 + 1)(1 - s)^2 = t^2,$$

so,

$$(1 - s)^2 = t^2 (1 - (1 - s)^2) \quad \text{and} \quad t^2 = \frac{(1 - s)^2}{1 - (1 - s)^2}.$$

Finally from the equality above we obtain

$$t = \frac{1 - s}{\sqrt{1 - (1 - s)^2}}.$$

Therefore there is an inverse function h'^{-1} as follows:

$$h'^{-1}(s) = t(s) = \frac{(1 - s)}{\sqrt{1 - (1 - s)^2}}. \quad (12)$$

Thus, the conjugate of the dislocation hyperbolic function is

$$\begin{aligned} h^*(s) &= \inf_{t \in \mathbb{R}} \{ st(s) - h(t(s)) \} = \inf_{t \in \text{dom}(h)} \{ st(s) - h(t(s)) \} \\ &= \inf \left\{ s \left(\frac{(1 - s)}{\sqrt{1 - (1 - s)^2}} \right) - \left(\frac{(1 - s)}{\sqrt{1 - (1 - s)^2}} - \sqrt{\frac{(1 - s)^2}{1 - (1 - s)^2} + 1 + 1} \right) \right\} \\ &= \inf \left\{ \frac{s(1 - s)}{\sqrt{1 - (1 - s)^2}} - \frac{(1 - s)}{\sqrt{1 - (1 - s)^2}} + \sqrt{\frac{(1 - s)^2}{1 - (1 - s)^2} + 1 - 1} \right\} \\ &= \inf \left\{ \frac{s(1 - s) - (1 - s)}{\sqrt{1 - (1 - s)^2}} + \sqrt{\frac{(1 - s)^2 + 1 - (1 - s)^2}{1 - (1 - s)^2}} - 1 \right\} \\ &= \inf \left\{ \frac{(s - 1)(1 - s)}{\sqrt{1 - (1 - s)^2}} + \frac{1}{\sqrt{1 - (1 - s)^2}} - 1 \right\} \\ &= \inf \left\{ \frac{-(1 - s)^2}{\sqrt{1 - (1 - s)^2}} + \frac{1}{\sqrt{1 - (1 - s)^2}} - 1 \right\} \\ &= \inf \left\{ \frac{1 - (1 - s)^2}{\sqrt{1 - (1 - s)^2}} - 1 \right\}. \end{aligned} \quad (13)$$

On the other hand, we know

$$\sqrt{1 - (1 - s)^2} \leq \frac{1 - (1 - s)^2}{\sqrt{1 - (1 - s)^2}}, \quad \forall s \in (0, 2). \quad (14)$$

Finally, let us consider (14) in (13), so we get

$$h^*(s) = \sqrt{1 - (1 - s)^2} - 1, \quad \forall s \in (0, 2). \quad (15)$$

We obtain, $-1 \leq h^*(s) \leq 0$ for $0 \leq s \leq 1$.

Now, since $h^*(1) = 0$, we obtain $\max \{h^*(s) : 0 \leq s \leq 2\} = h^*(1) = 0$ and

$$(0, 2) = \text{ri}(\text{dom } h^*) \subset \text{range } h' \subset \text{dom } h^* = [0, 2]. \quad (16)$$

To obtain expression (16) we follow an analysis similar to the Section 24 of [26], Proposition 3.1 of [24] and Section 3 of [23].

3.3. The kernel for the dislocation hyperbolic function

In this section we are going to define the dislocation hyperbolic kernel function (DHKF). Now, given $h \in \Psi_H$, we introduce the function $\varphi : [0, 2] \rightarrow \mathbb{R}$ as

$$\varphi(s) = -h^*(s) = 1 - \sqrt{1 - (1 - s)^2}, \quad (17)$$

The function h^* is concave and hence $\varphi = -h^*$ is convex, see Figure 3.4.

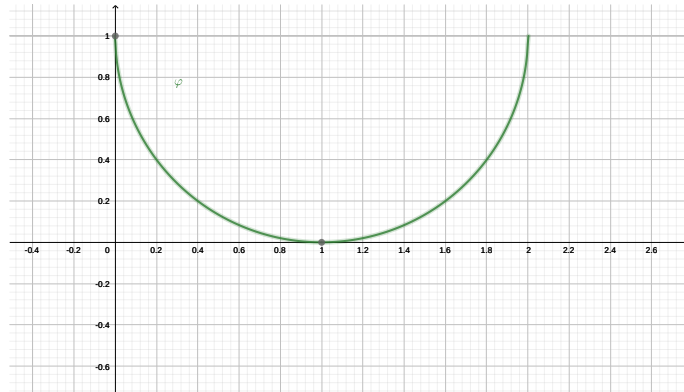
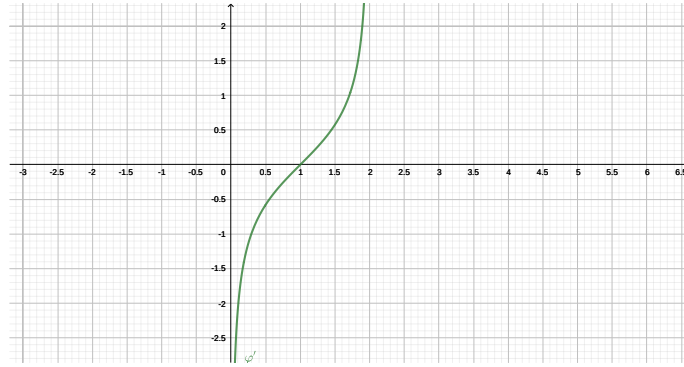
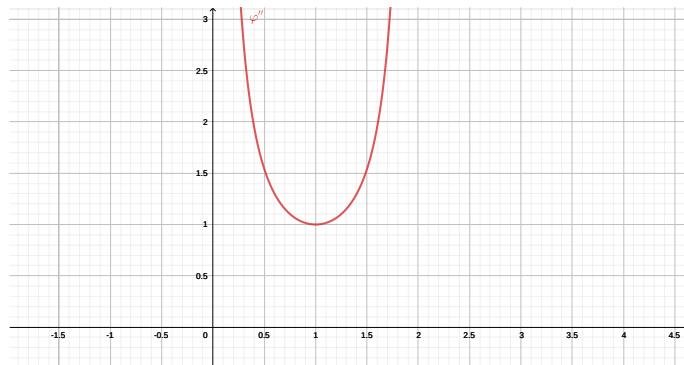
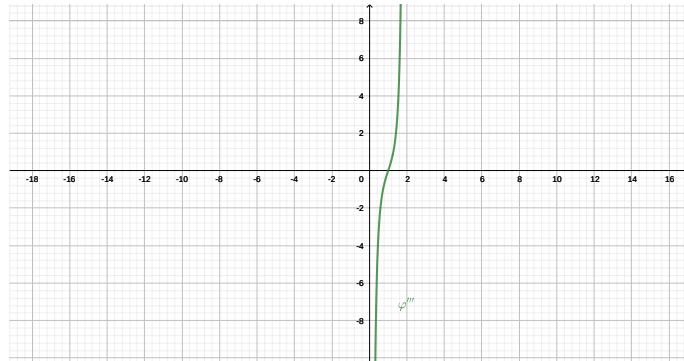


Figure 3.4: Function $\varphi(s)$

The first, second and third derivative of φ with respect to s are, respectively:

$$\varphi'(s) = \frac{-(1 - s)}{\sqrt{1 - (1 - s)^2}}, \quad \varphi''(s) = \frac{1}{(1 - (1 - s)^2)^{\frac{3}{2}}}, \quad \varphi'''(s) = \frac{-3(1 - s)}{(1 - (1 - s)^2)^{\frac{5}{2}}},$$

for all $s \in (0, 2)$, see Figures 3.5, 3.6 and 3.7 respectively.

Figure 3.5: Function $\varphi'(s)$ Figure 3.6: Function $\varphi''(s)$ Figure 3.7: Function $\varphi'''(s)$

The function φ has the following properties:

Proposition 3.1. *Let $h \in \Psi_H$. Then the function φ is a strictly convex differentiable function in the set $(0, 2)$ which satisfies*

$$\varphi(1) = \varphi'(1) = 0 \quad \text{and} \quad \lim_{s \rightarrow 0^+} \varphi'(s) = -\infty. \quad (18)$$

Proof. The function φ is strictly convex, i.e.,

$$\varphi''(s) = \frac{1}{(1 - (1 - s)^2)^{\frac{3}{2}}} > 0, \quad \forall s \in (0, 2).$$

The proof of (18) is similar to the proof of Proposition 3.1 of [24]. □

Proposition 3.2.

- (K1) (i) $\varphi'(s) < 0, \quad \forall s \in (0, 1).$
(ii) $\varphi'(s) > 0, \quad \forall s \in (1, 2).$
- (K2) $\lim_{s \rightarrow 2^-} \varphi'(s) = +\infty.$
- (K3) (i) $\varphi'''(s) < 0, \quad \forall s \in (0, 1).$
(ii) $\varphi'''(1) = 0,$
(iii) $\varphi'''(s) > 0, \quad \forall s \in (1, 2).$
- (K4) (i) $\lim_{s \rightarrow 0^+} \varphi(s) = 1.$
(ii) $\lim_{s \rightarrow 2^-} \varphi(s) = 1.$

Proof. The demonstrations are direct. □

After all of the above, we now propose the following definition.

Definition 3.3. A univariate function $\varphi : (0, 2) \rightarrow \mathbb{R}$ is called the *dislocation hyperbolic kernel function* if $\varphi(s)$ is continuously differentiable and the following conditions hold:

- (i) $\varphi(1) = \varphi'(1) = 0;$
(ii) $\varphi''(s) > 0;$
(iii) $\lim_{s \rightarrow 0^+} \varphi(s) = 1$ and $\lim_{s \rightarrow 2^-} \varphi(s) = 1.$

We can see that our function kernel φ does not have the right or left coercivity property. Also, due to the condition (iii) in Definition 3.3, we see that the function $\varphi(s)$ does not possess the general property of the barrier function. Something similar to our Definition 3.3 can be seen in [5] and [12]. In these works, the kernel functions have only right-hand coercivity.

4. Applications of DHF

4.1. Information measures

This section is based on the work [8]. We propose a function based on information measures function studied in [8]. For any $h : \mathbb{R}_+ \rightarrow \mathbb{R}$ which is concave and normalized, i.e.,

$$h(1) = 0, \tag{19}$$

and the adjoint function w , defined by,

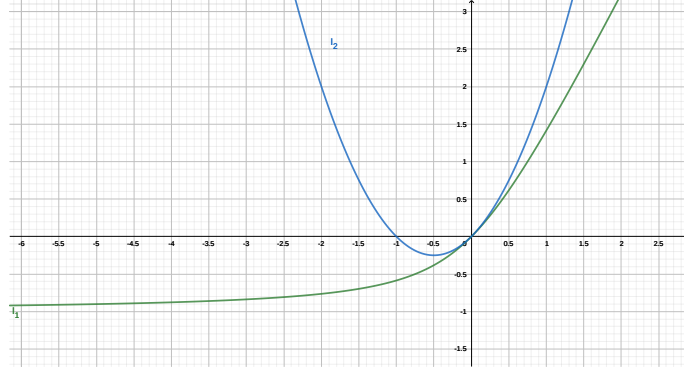
$$w(t) = t h\left(\frac{1}{t}\right), \quad \forall t \in \mathbb{R}_+. \tag{20}$$

4.2. Dislocation hyperbolic quadratic function

In the work of Kort and Bertsekas [15] a class of functions is proposed, with this class of functions an augmented Lagrangian type algorithm is proposed and its convergence is ensured. In this section, we propose the function ϕ_1 which belongs to the class of functions of Kort and Bertsekas. This new function is defined as,

$$\phi_1 : \mathbb{R} \rightarrow \mathbb{R}, \quad \phi_1(t) = \begin{cases} t + \sqrt{t^2 + 1} - 1, & t < 0 \\ t + t^2, & t \geq 0 \end{cases}$$

see Figure 4.1.

Figure 4.1: Function $\phi_1(t)$

We note the following properties of $\phi_1(x)$:

- (a1) $\phi_1''(t) > 0, \forall t \in \mathbb{R}$, (a2) $\phi_1(0) = 0$, (a3) $\phi_1'(0) = 1$
 (a4) $\lim_{t \rightarrow -\infty} \phi_1(t) = -1$, (a5) $\lim_{t \rightarrow \infty} \phi_1'(t) = \infty$.

5. Applications of DHKF

5.1. Hyperbolic distance

This section is based on Subsection 1.2 of [14]. Let Φ_1 be the set of functions $\varphi_1 : (0, \infty) \rightarrow [0, \infty)$ which satisfy the following properties:

- (P1) φ_1 is strictly convex and thrice continuously differentiable.
 (P2) $\varphi_1(1) = 0$.
 (P3) $\varphi_1'(1) = 0$.
 (P4) $\varphi_1''(1) > 0$.
 (P5) $\lim_{t \rightarrow 0} \varphi_1'(t) = -\infty$.

Define $d_{\varphi_1} : \mathbb{R}_{++}^n \times \mathbb{R}_{++}^n \rightarrow \mathbb{R}_+$ as $d_{\varphi_1}(x, y) = \sum_{j=1}^n y_j \varphi_1\left(\frac{x_j}{y_j}\right)$.

When $\varphi_1 \in \Phi_1$, d_{φ_1} is said to be a φ_1 -divergence. Now, in our case, since φ has the properties (K1)–(K4) and the Proposition 3.1 then check the conditions (P1)–(P5). Then $\varphi \in \Phi_1$ and the dislocation hyperbolic kernel distance function (DHKDF) is defined by $d_\varphi : \mathbb{R}_+^n \times \mathbb{R}_{++}^n \rightarrow \mathbb{R}$ as

$$d_\varphi(x, x^k) = \sum_{i=1}^p x_i^k \varphi\left(\frac{x_i}{x_i^k}\right) = \sum_{i=1}^p x_i^k \left(1 - \sqrt{1 - \left(1 - \frac{x_i}{x_i^k}\right)^2}\right),$$

i.e., d_φ is said to be a φ -divergence.

Lemma 5.1. *Let $\varphi \in \Phi_1$.*

- (a) $d_\varphi(x, y) \geq 0$ and equality holds iff $x = y$;
 (b) $d_\varphi(x, y)$ is jointly convex in (x, y) .

Proof. (a) Since φ is convex, we have

$$\varphi\left(\frac{x_j}{y_j}\right) \geq \varphi(1) + \varphi'(1)\left(\frac{x_j}{y_j} - 1\right), \quad j = 1, \dots, n,$$

since $\varphi \in \Phi_1$, and by (P2) and (P3), it follows from the inequality above that

$$\varphi\left(\frac{x_j}{y_j}\right) \geq 0, \quad j = 1, \dots, n,$$

so,

$$d_\varphi(x, y) = \sum_{j=1}^n y_j \varphi\left(\frac{x_j}{y_j}\right) \geq 0.$$

If $x = y$, then by (P2) it follows that

$$d_\varphi(x, x) = \sum_{j=1}^n x_j \varphi\left(\frac{x_j}{x_j}\right) = \sum_{j=1}^n x_j \varphi(1) = 0, \quad \text{i.e. } d_\varphi(x, x) = 0.$$

If $d_\varphi(x, y) = 0$, then

$$d_\varphi(x, y) = \sum_{j=1}^n y_j \varphi\left(\frac{x_j}{y_j}\right) = \sum_{j=1}^n y_j \left(1 - \sqrt{1 - \left(1 - \frac{x_j}{y_j}\right)^2}\right) = 0,$$

so,

$$x_j = y_j, \quad j = 1, \dots, n.$$

(b) We show that $l(x, t) = t\varphi\left(\frac{x}{t}\right)$ is jointly convex in (x, t) . From the convexity of φ , and $\forall (x_1, t_1), (x_2, t_2) \in \mathbb{R}_{++}^2$ and $c \in (0, 1)$, from all this it follows that

$$\begin{aligned} \varphi\left(\frac{cx_1 + (1-c)x_2}{ct_1 + (1-c)t_2}\right) &= \varphi\left(\frac{ct_1}{ct_1 + (1-c)t_2} \frac{x_1}{t_1} + \frac{(1-c)t_2}{ct_1 + (1-c)t_2} \frac{x_2}{t_2}\right) \\ &\leq \frac{c}{ct_1 + (1-c)t_2} t_1 \varphi\left(\frac{x_1}{t_1}\right) + \frac{(1-c)}{ct_1 + (1-c)t_2} t_2 \varphi\left(\frac{x_2}{t_2}\right), \end{aligned}$$

then it follows that

$$l(cx_1 + (1-c)x_2, ct_1 + (1-c)t_2) \leq cl(x_1, t_1) + (1-c)l(x_2, t_2),$$

what had to be shown. □

5.2. New self-concordant functions

The $\left(\left(\frac{3}{4}\right)^{\frac{3}{4}}\right)$ -self-concordant dislocation hyperbolic kernel function

The function φ is a $\left(\left(\frac{3}{4}\right)^{\frac{3}{4}}\right)$ -self-concordant dislocation hyperbolic kernel function for $\frac{1}{2} < s < 1$.

We have

$$\begin{aligned} \frac{|\varphi'''(s)|}{2(\varphi''(s))^{\frac{3}{2}}} &= \frac{\left| \frac{-3(1-s)}{(1-(1-s)^2)^{\frac{5}{2}}} \right|}{2 \left(\frac{1}{(1-(1-s)^2)^{\frac{3}{2}}} \right)^{\frac{3}{2}}} = \frac{3(1-s)(1-(1-s)^2)^{\frac{9}{4}}}{2(1-(1-s)^2)^{\frac{5}{2}}} \\ &= \frac{3(1-s)}{2(1-(1-s)^2)^{\frac{1}{4}}} \end{aligned} \quad (21)$$

On the other hand, we know that,

$$0 < \frac{3(1-s)}{2(1-(1-s)^2)^{\frac{1}{4}}} < \frac{3}{4(1-(1-s)^2)^{\frac{1}{4}}} \quad (22)$$

and

$$\frac{1}{(1-(1-s)^2)^{\frac{1}{4}}} < \frac{1}{\left(\frac{3}{4}\right)^{\frac{1}{4}}}. \quad (23)$$

From (21), (22) and (23), we get $\frac{|\varphi'''(s)|}{2(\varphi''(s))^{\frac{3}{2}}} < \left(\frac{3}{4}\right)^{\frac{3}{4}}$.

The $\left(2^{\frac{1}{4}}\right)$ -self-concordant dislocation hyperbolic kernel barrier function

The function φ is a $\left(2^{\frac{1}{4}}\right)$ -self-concordant dislocation hyperbolic kernel barrier function for $0 < s < 1$. We have

$$\begin{aligned} \frac{|\varphi'(s)|}{(\varphi''(s))^{\frac{1}{2}}} &= \frac{\left| \frac{-(1-s)}{(1-(1-s)^2)^{\frac{1}{2}}} \right|}{\left(\frac{1}{(1-(1-s)^2)^{\frac{3}{2}}} \right)^{\frac{1}{2}}} = \frac{\frac{(1-s)}{(1-(1-s)^2)^{\frac{1}{2}}}}{\frac{1}{(1-(1-s)^2)^{\frac{3}{4}}}} \\ &= \frac{(1-s)(1-(1-s)^2)^{\frac{3}{4}}}{(1-(1-s)^2)^{\frac{1}{2}}} = (1-s)(1-(1-s)^2)^{\frac{1}{4}} \\ &= (1-s)s^{\frac{1}{4}}(2-s)^{\frac{1}{4}} < 2^{\frac{1}{4}}. \end{aligned}$$

6. Conclusions and future work

We present a new kernel function and a new proximal type distance. Using our Proposition 3.1 and properties K1-K4 our future work is to find new suitable properties to propose a proximal point algorithm and subsequently ensure a convergence theory for this proximal point algorithm based on our new kernel function.

Acknowledgements. The first author was supported by PDR10/FAPERJ, E-17/2022, Brazil; the second author by COPPETEC Foundation, Brazil and the fourth author is thankful to Fundação de Amparo à Pesquisa do Estado do Rio de Janeiro (FAPERJ) for their financial support E-26/2021 - Auxílio Básico à Pesquisa, APQ1.

References

- [1] M. Achache: *A new primal-dual path-following method for convex quadratic programming*, Comp. Appl. Math. 25 (2006) 97–110.
- [2] A. Auslender, M. Teboulle, S. Ben-Tiba: *Interior proximal and multiplier methods based on second order homogeneous kernels*, Math. Oper. Res. 24 (1999) 645–668.
- [3] A. M. Bagirov, N. Karmitsa, S. Taheri: *Partitional Clustering via Nonsmooth Optimization*, Springer, Cham (2020).
- [4] A. M. Bagirov, B. Ordin, G. Ozturk, A. E. Xavier: *An incremental clustering algorithm based on hyperbolic smoothing*, Pattern Recognition 61 (2015) 219–241.
- [5] Y. Q. Bai, M. El Ghami, C. Roos: *A new efficient large-update primal-dual interior-point method based on a finite barrier*, SIAM J. Optim. 13 (2003) 766–782.
- [6] Y. Q. Bai, M. El Ghami, C. Roos: *A comparative study of kernel functions for primal-dual interior point algorithms in linear optimization*, SIAM J. Optim. 15 (2004) 101–128.
- [7] Y. Q. Bai, W. Xie, J. Zhang: *New parameterized kernel functions for linear optimization*, J. Global Optim. 54 (2012) 353–366.
- [8] A. Ben-Tal, A. Ben-Israel, M. Teboulle: *Certainty equivalents and information measures: duality and extremal principles*, J. Math. Analysis Appl. 157 (1991) 211–236.
- [9] A. Ben-Tal, M. Teboulle: *Penalty function and duality in stochastic programming via ϕ -divergence functionals*, Math. Oper. Res. 12 (1987) 224–240.
- [10] R. Beran: *Minimum Hellinger distances estimates for parametric models*, Ann. Statist. 5 (1977) 445–463.
- [11] C. Chen, O. L. Mangasarian: *Smoothing methods for convex inequalities and linear complementarity problems*, Math. Programming 71 (1995) 51–69.
- [12] S. Fathi-Hafshejani, A. F. Jahromi, M. R. Peyghami, S. Chen: *Complexity of interior point for a class of linear complementarity problems using a kernel function with trigonometric growth term*, J. Optim. Theory Appl. 178 (2018) 935–949.
- [13] C. C. Gonzaga, R. A. Castillo: *A nonlinear programming algorithm based on non-coercive penalty function*, Math. Programming 96 (2003) 87–101.
- [14] A. N. Iusem, M. Teboulle: *Convergence rate analysis of nonquadratic proximal methods for convex and linear programming*, Math. Oper. Res. 20 (1995) 657–677.
- [15] B. W. Kort, D. P. Bertsekas: *A new penalty function method for constrained minimization*, Proc. 1972 IEEE Conf. Decision and Control (1972) 162–166.
- [16] S. Kullback, R. A. Leibler: *On information and sufficiency*, Ann. Math. Statist. 22 (1951) 79–86.
- [17] L. Mallma-Ramirez: *The Hyperbolic Augmented Lagrangian Algorithm*, Ph. D. Thesis, Federal University of Rio de Janeiro/COPPE, Rio de Janeiro, Brazil (2022); <https://www.cos.ufrj.br/uploadfile/publicacao/3038.pdf>.
- [18] L. Mallma-Ramirez, N. Maculan, E. A. Xavier, V. L. Xavier: *Convergence analysis of the hyperbolic augmented Lagrangian algorithm*, Technical Report, PESC-COPPE-UFRJ, ES-2991/21 (2021); <https://www.cos.ufrj.br/uploadfile/publicacao/2991.pdf>.
- [19] Y. E. Nesterov, A. S. Nemirovskii: *Interior Point Polynomial Algorithms in Convex Programming*, SIAM Studies in Applied Mathematics, Philadelphia (1994).

- [20] J. Peng, C. Roos, T. Terlaky: *Self-regular functions and new search directions for linear and semidefinite optimization*, Math. Programming 93 (2002) 129–171.
- [21] M. R. Peyghami, S. F. Hafshejani: *Complexity analysis of an interior-point algorithm for linear optimization based on a new proximity function*, Numer. Algorithms 67 (2014) 33–48.
- [22] R. A. Polyak: *Log-sigmoid multipliers method in constrained optimization*, Ann. Oper. Res. 101 (2001) 427–460.
- [23] R. A. Polyak: *Nonlinear rescaling vs. smoothing technique in convex optimization*, Math. Programming 92 (2002) 197–235.
- [24] R. Polyak, M. Teboulle: *Nonlinear rescaling and proximal-like methods in convex optimization*, Math. Programming 76 (1997) 265–284.
- [25] J. W. Pratt: *Risk aversion in the small and in the large*, Econometrica 32 (1964) 122–136.
- [26] R. T. Rockafellar: *Convex Analysis*, Princeton University Press, Princeton (1970).
- [27] A. E. Xavier: *Penalização Hiperbólica – Um Novo Método para Resolução de Problemas de Otimização*, Master's Thesis, Federal University of Rio de Janeiro/COPPE, Rio de Janeiro, Brazil (1982).
- [28] A. E. Xavier: *Penalização Hiperbólica*, Ph.D. Thesis, Federal University of Rio de Janeiro/COPPE, Rio de Janeiro, Brazil (1992).
- [29] A. E. Xavier: *Hyperbolic penalty: a new method for nonlinear programming with inequalities*, Int. Trans. Oper. Res. 8 (2001) 659–671.
- [30] A. E. Xavier: *The hyperbolic smoothing clustering method*, Pattern Recognition 43 (2010) 731–737.
- [31] W. I. Zangwill: *Non-linear programming via penalty function*, Manage. Science 13 (1967) 344–358.